

Digital Security of Physical Objects

Slava Voloshynovskiy
Stochastic Information Processing Group
University of Geneva
Switzerland

Outline

- ▶ Physical object security
- ▶ Why not traditional security?
- ▶ Proposed solutions for
 - ▶ Object recognition
 - ▶ Design verification
 - ▶ Physical uncloneable functions
- ▶ Conclusions

SIP group at glance

▶ Basic facts:

- ▶ Founded in 1998
- ▶ Currently 8 people
- ▶ Group produced 10 PhDs

▶ Main background:

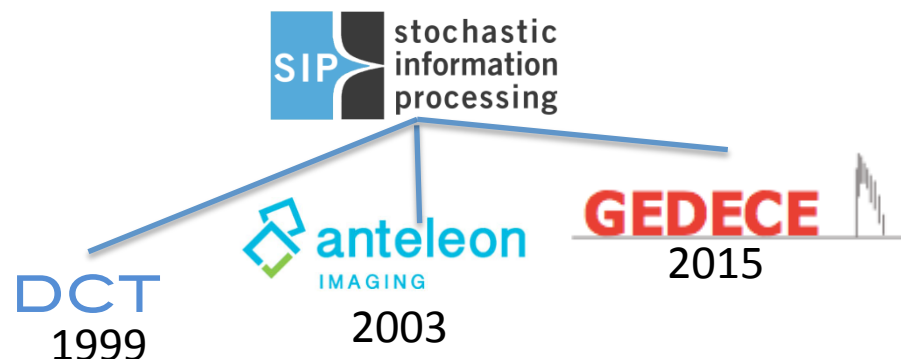
- ▶ Statistical image processing
- ▶ Information theory
- ▶ Machine learning

▶ Expertise in:

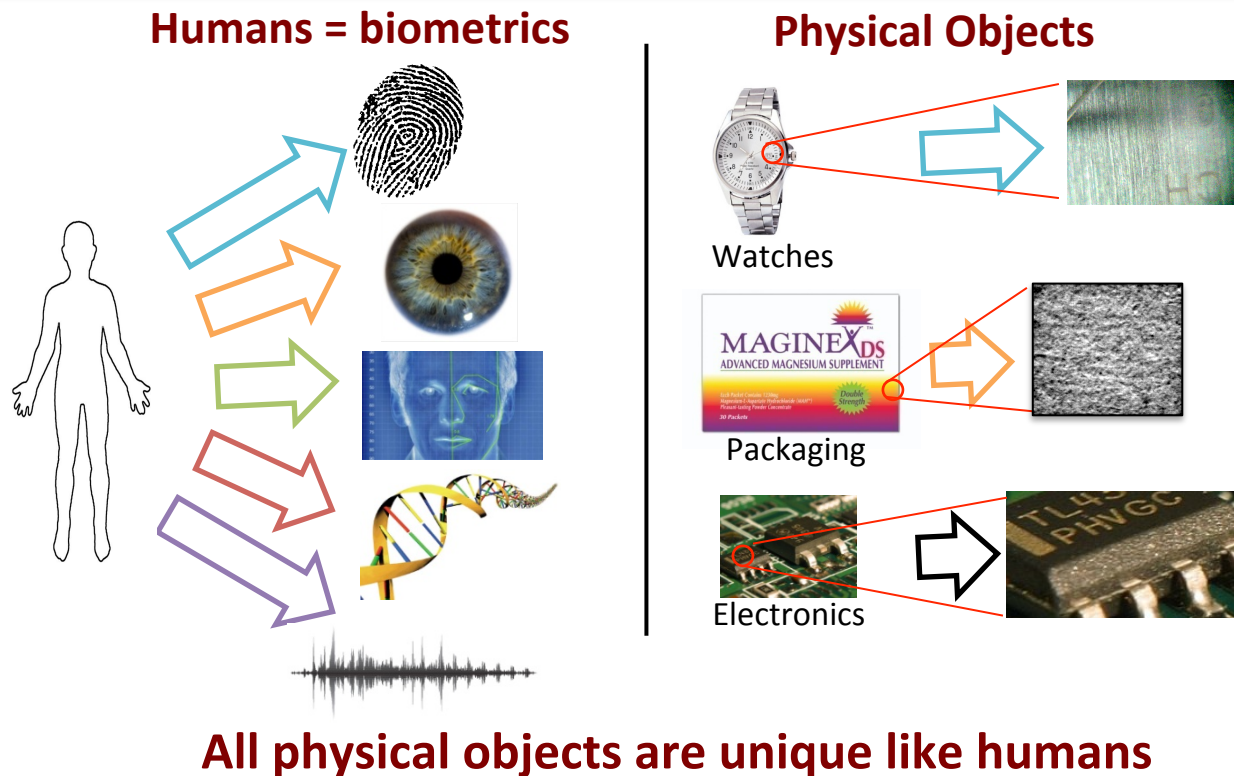
- ▶ Digital watermarking
- ▶ Fingerprinting
- ▶ Physical object security

▶ Technology valorization:

- ▶ 6 licensed patent families
- ▶ 3 spin-offs



1. Physical object security



Why security is important?

- Damage of brand reputation
- Loss of profit
- Danger for life
-

Main security concerns

- Authenticity
- Origin (identification)
- Ownership
- Track and trace

2. Why not “traditional” security

Main restriction of existing security technologies for physical objects:

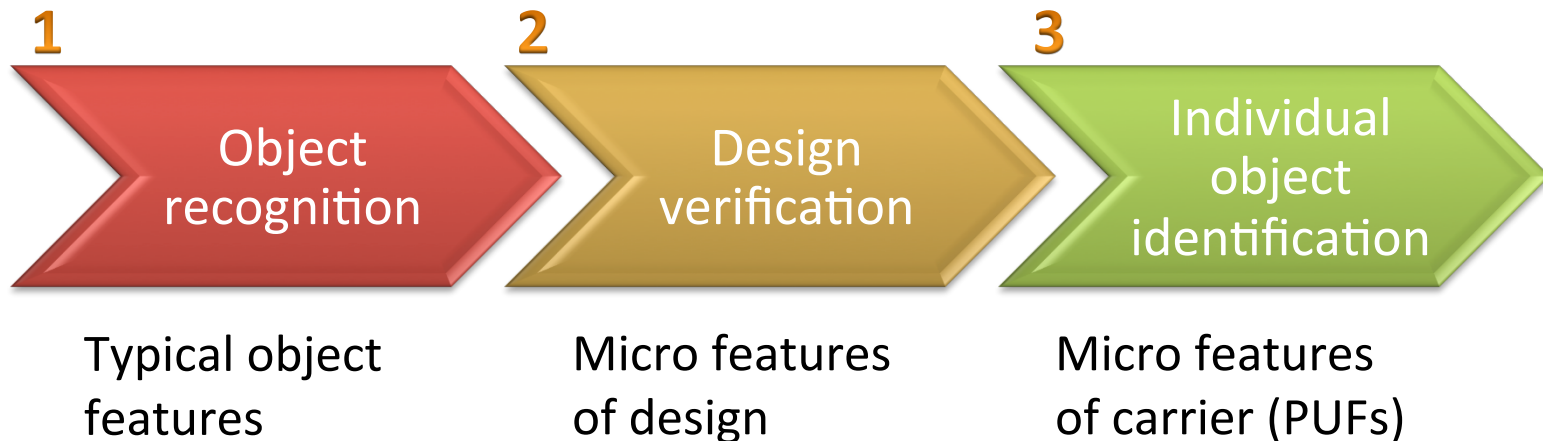
- **Proprietary technologies** (rare or expensive materials, inks, holograms, etc.)
 - obsolete and easy to clone by modern means
 - expensive for mass markets
 - special equipment or special knowledge of original features are required
- **Crypto security**
 - not directly applicable to noisy data
 - very sensitive to light and geometrical variations
- **RFID/Connected devices/Internet of Things**
 - still quite expensive
 - serious security wholes

2. Why not “traditional” security

Requirements to modern physical object security:

- **easy to verify authenticity but difficult to clone**
 - cloning should be economically inefficient
- **non-proprietary: based on physical-crypto principles**
 - protection mechanism is assumed to be public
- **no special equipment required**
 - preferably on mobile phone (in possession of everyone)
- **no special training required**
 - any user can validate it
- **cheap and scalable to mass markets**
 - millions or billions of products
- **non-invasive**
 - products and production should not be modified

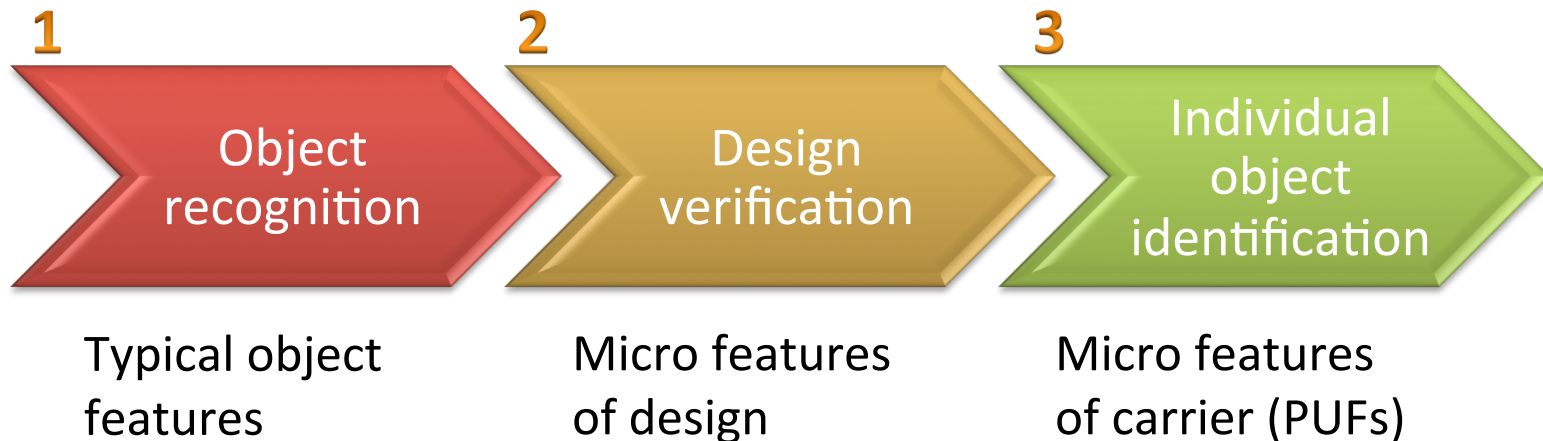
3. Product security: a framework



Three levels of security:

- **Object recognition**
 - Printed/reproduced visible features typical for all object of the same category

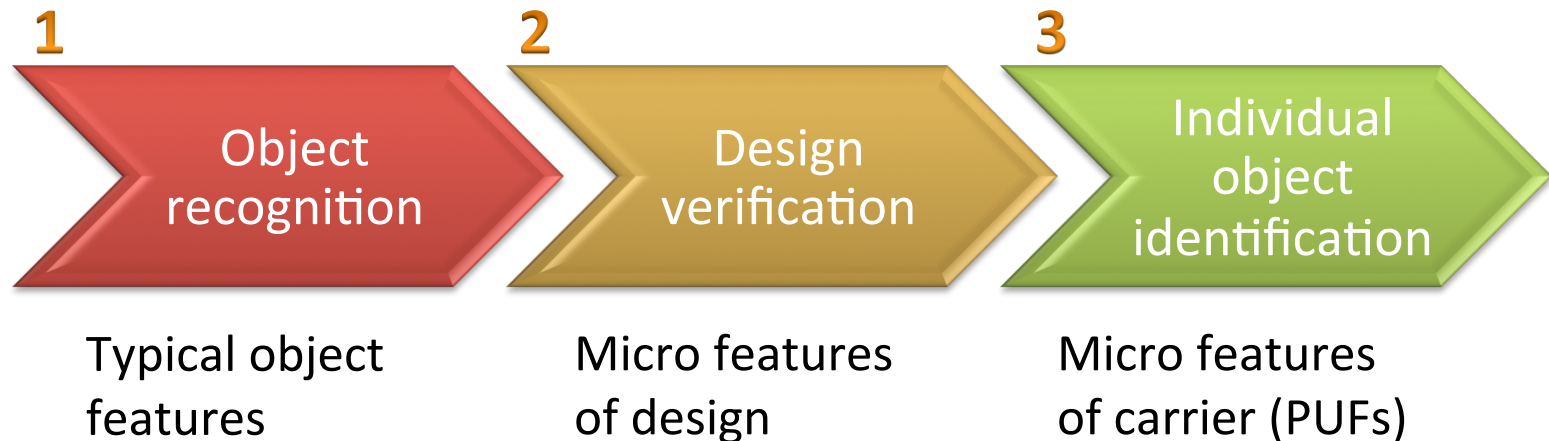
3. Product security: a framework



Three levels of security:

- **Object recognition**
 - Printed/reproduced visible features typical for all object of the same category
- **Design verification**
 - Features of probe are verified wrt features of original template

3. Product security: a framework



Three levels of security:

- **Object recognition**
 - Printed/reproduced visible features typical for all object of the same category
- **Design verification = digital forensics**
 - Features of probe are verified wrt features of original template
- **Individual object identification**
 - Features of probe carrier are tested wrt features of enrolled PUFs

3.1. Stage 1: object recognition

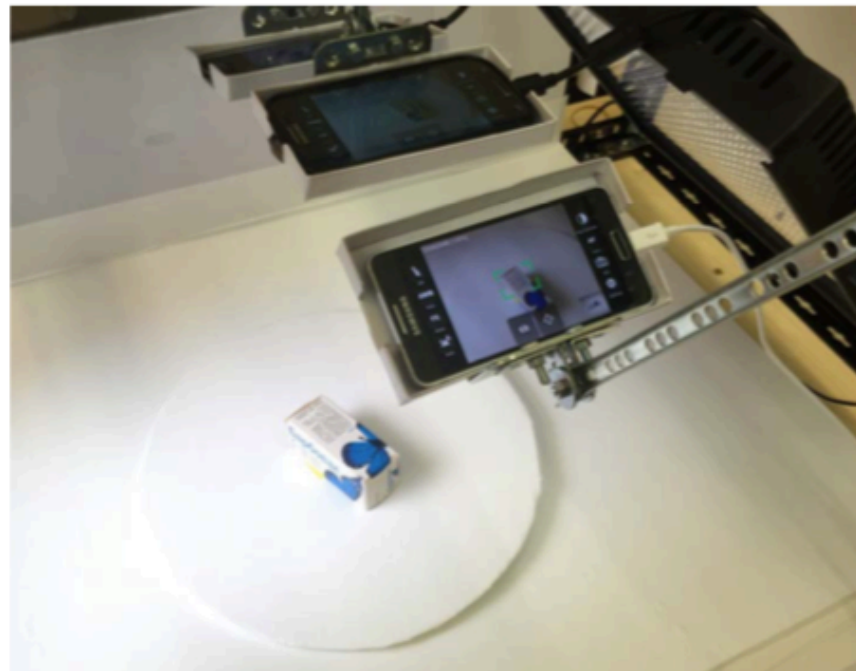
Main specs to object recognition:

- Mobile phones
- Very accurate
- Fast and scalable to millions
- Invariant to observation conditions such as light, geometry, etc

Experimental dataset



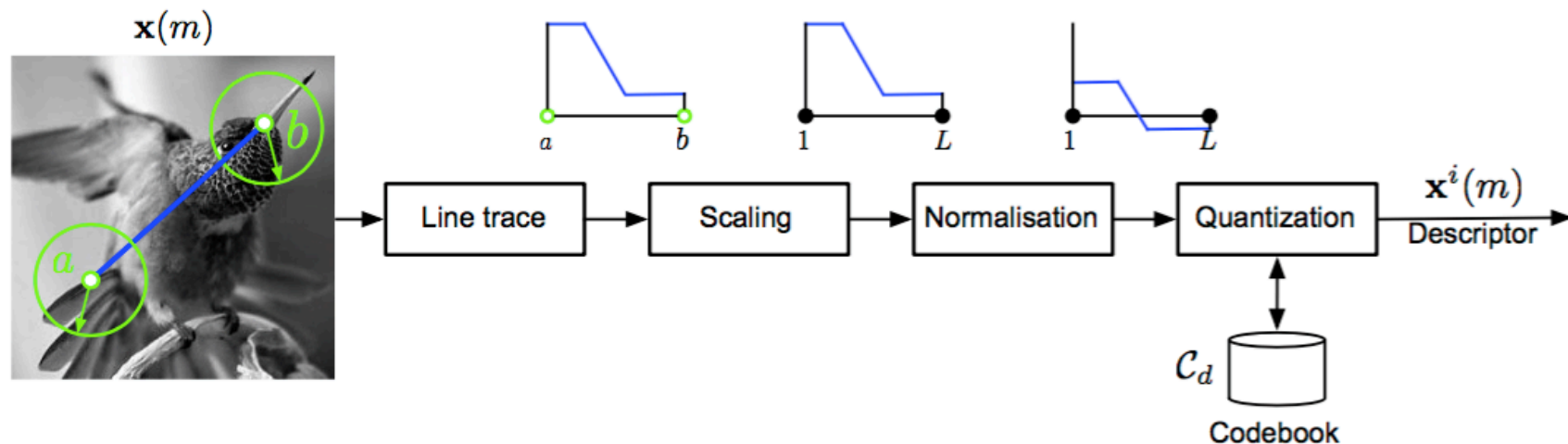
Enrollment system



3.1. Stage 1: object recognition (universal SketchPrint descriptor)

SketchPrint main idea

Extract a sketch connecting two reference points

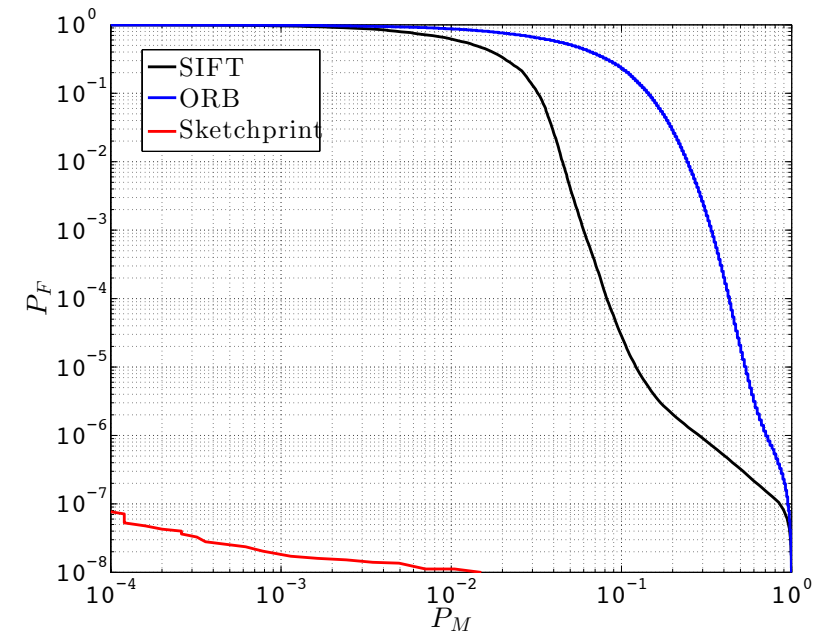
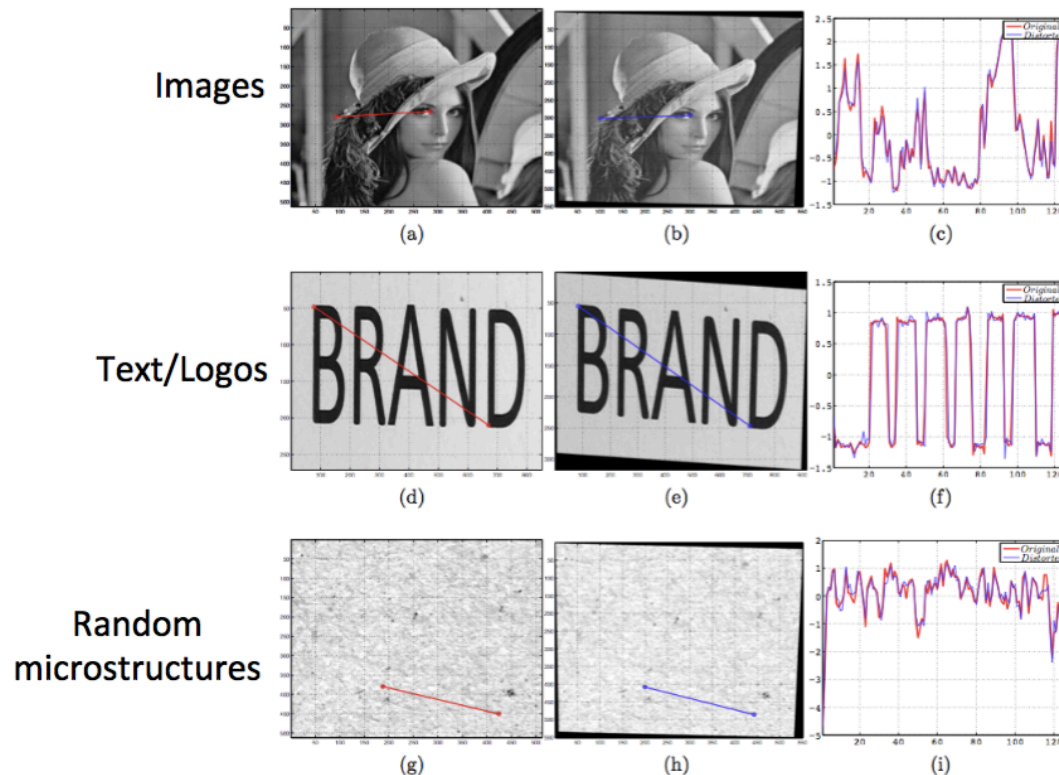


Main steps of SketchPrint:

- key-points detection
- SketchPrints extraction and filtering
- aggregation of many SketchPrint descriptors into one super-vector

3. Stage 1: object recognition (universal SketchPrint descriptor)

Performance and comparison to SOTA

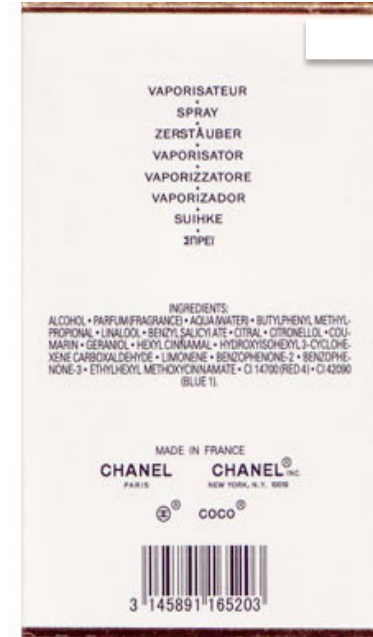


Remark

- SketchPrint considerably outperforms both SIFT and ORB
 - smaller number of descriptors per image \Rightarrow less memory

3.2. Stage 2: design verification

Given: a package



Question:

- Is this package authentic?

Remark: you have never seen it or remember its design roughly...

Your thinking: well....quality of print looks OK

.....logo seems OK

.....I buy it from a reputable vendor (incl web

.....so probably authentic!

3.2. Stage 2: design verification



Observation: if we know the original design, we can easily verify its authenticity.

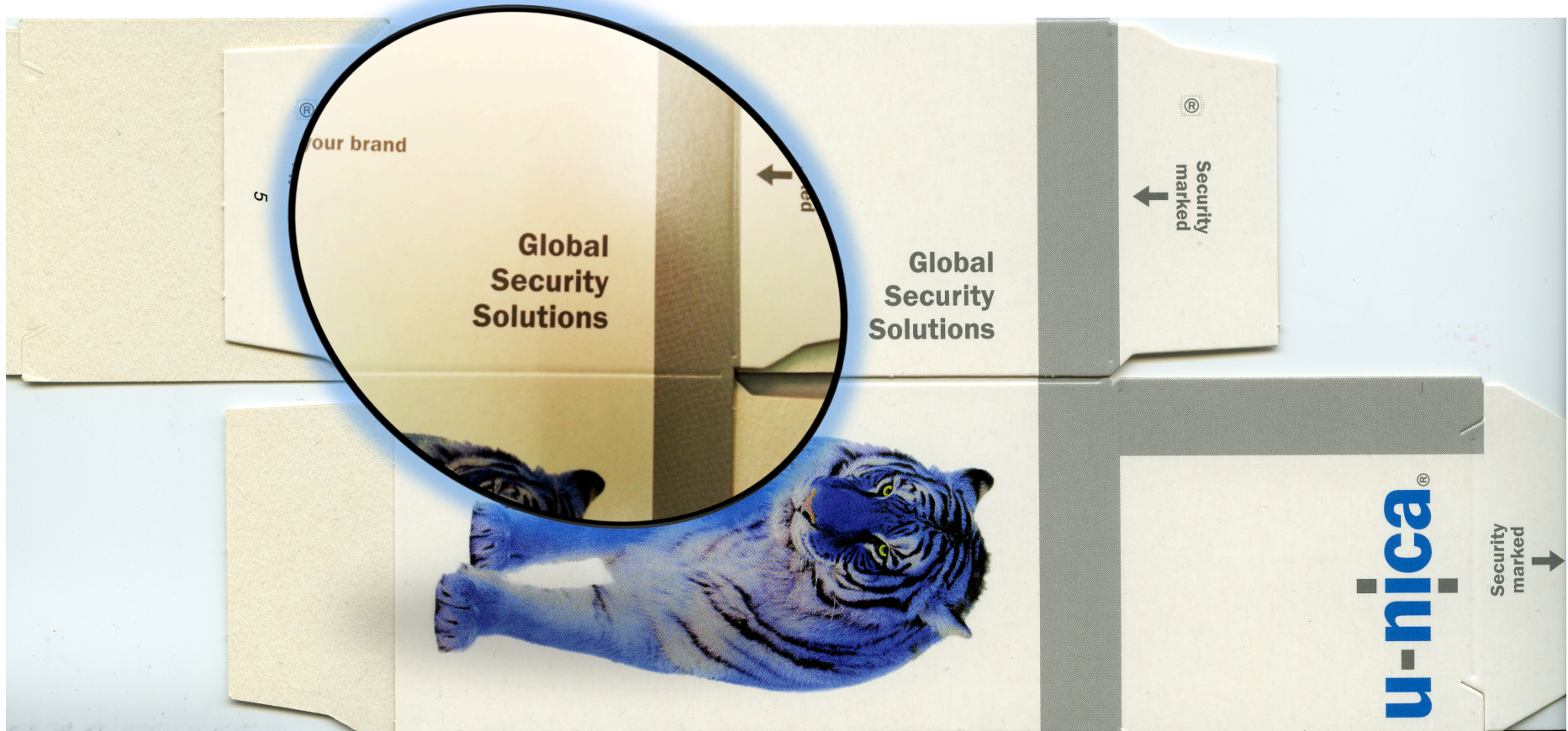
Question:

- Can we perform the design verification automatically?
- And how accurately (say with the precision about 10-15 microns)?

3.2. Stage 2: Automatic design verification on mobile phones

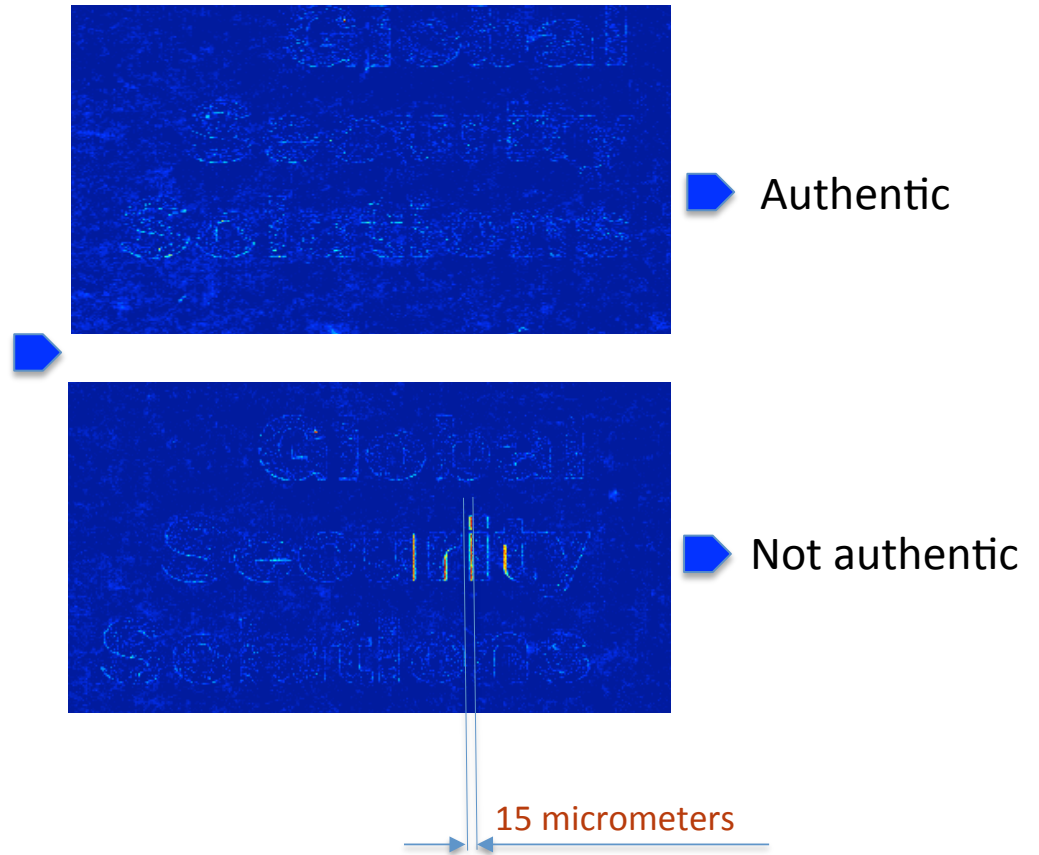
5'000 printed objects

Modified text



3.2. Stage 2: Automatic design verification on mobile phones

Text
Graphics
Images
Microstructures
Watches
Photos

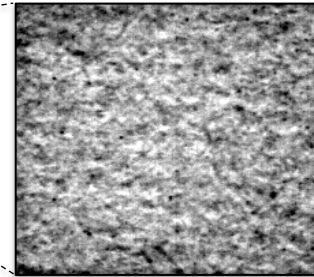


3.3. Stage 3: individual object recognition

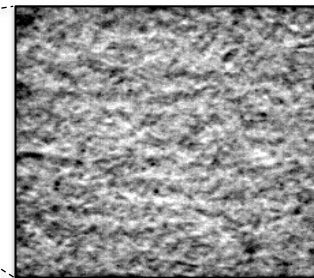
- **Question:** can we differentiate each individual object?

Paper microstructures = PUFs

Package 1

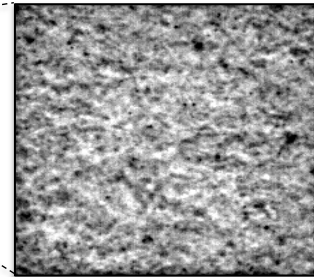


Package 2



•
•
•

Package M



Individually unique PUFs

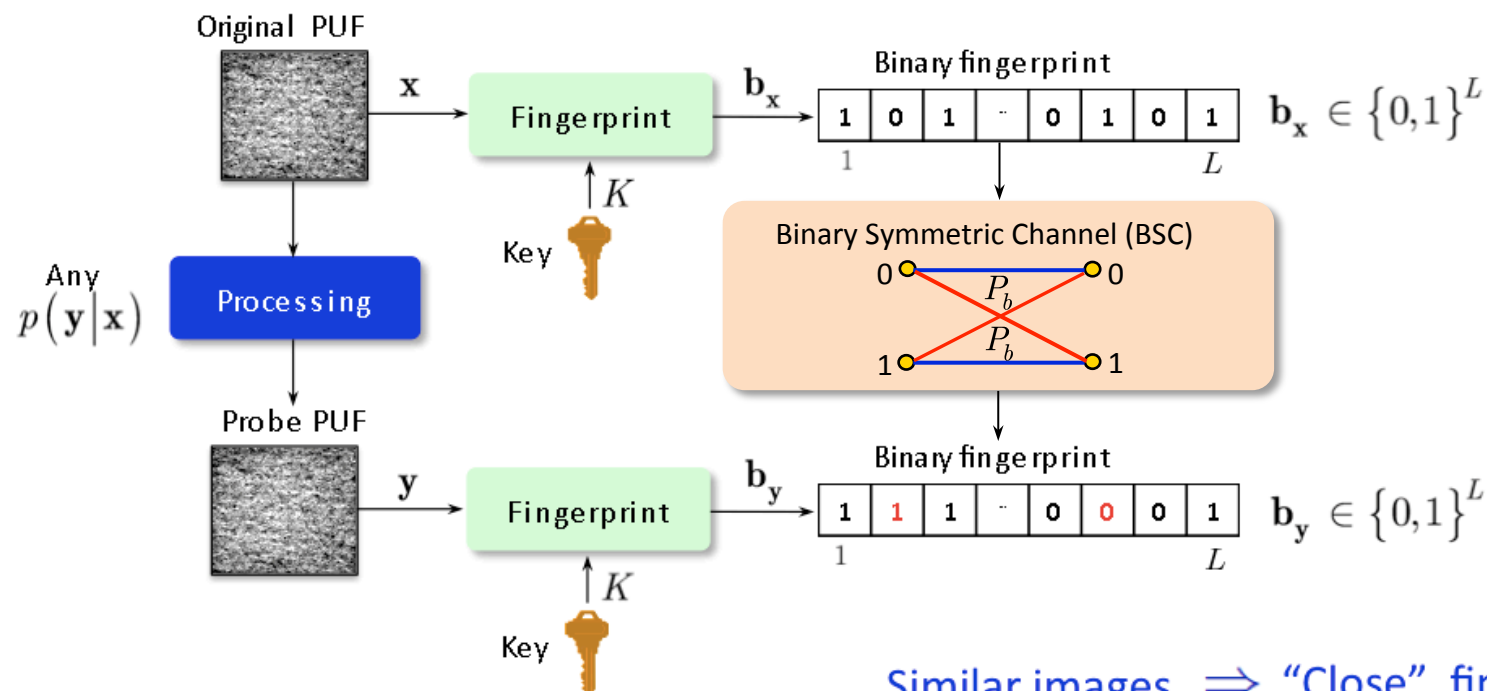
Visibly packages look identical

2. Stage 3: individual object recognition

- **Open issue: Big Data** (millions of objects with high-dimensional features)

Definition (Digital content fingerprinting)

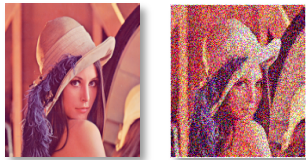
Digital content fingerprinting (*a.k.a. robust perceptual hashing*) is a technique for computing a compact robust, secure and private binary representation of image.



3.3. Stage 3: individual object recognition

Properties

Correct acceptance



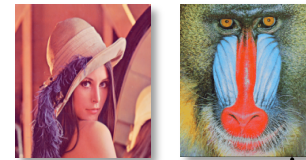
$\mathbf{x}(m)$ \mathbf{y}

$$\Pr[D^H(\mathbf{b}_u(m), \mathbf{b}_y) \leq \gamma L] \rightarrow 1$$

Binomial distribution

$$D^H(\mathbf{b}_u(m), \mathbf{b}_y) \sim B(L, P_b)$$

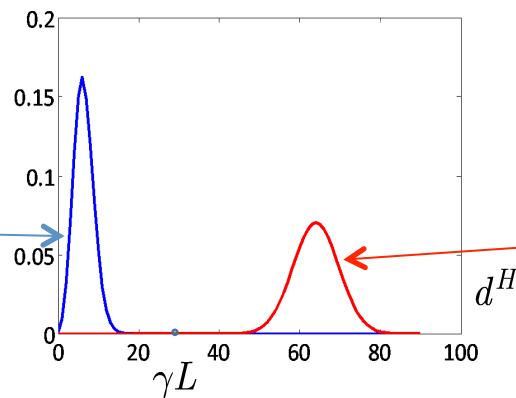
Correct rejection



$\mathbf{x}(m)$ $\mathbf{x}(m')$

$$\Pr[D^H(\mathbf{b}_u(m), \mathbf{b}_x(m')) \leq \gamma L] \rightarrow 0$$

Hypothesis testing



Binomial distribution

$$D^H(\mathbf{b}_u(m), \mathbf{b}_y) \sim B\left(L, \frac{1}{2}\right)$$

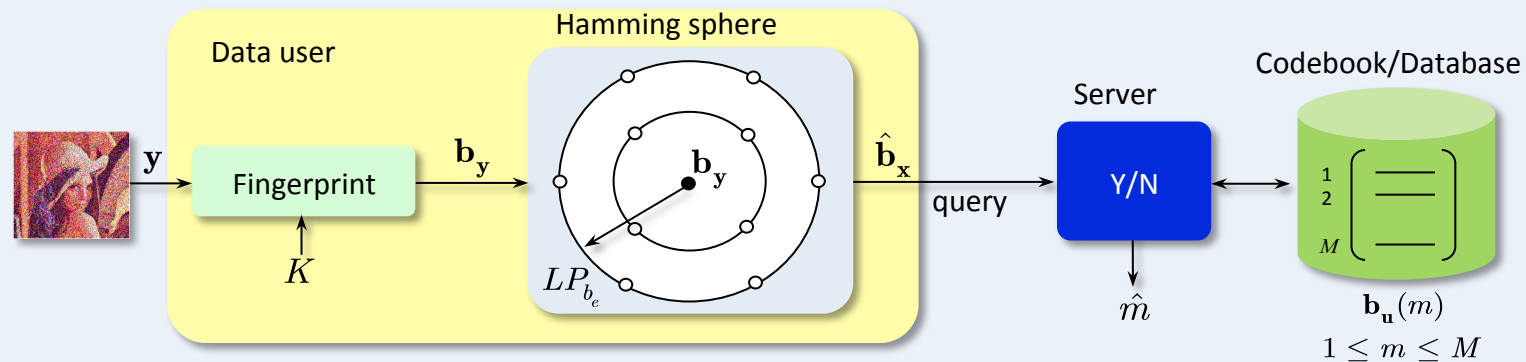
3.3. Stage 3: individual object recognition

- Fast search

Hamming sphere decoding

Observation: the most likely codewords $\mathbf{b}_u(\hat{m})$ are within a Hamming sphere with radius γL around \mathbf{b}_y .

Identification = codeword presence verification



4. Conclusion

- **Physical object security = multidisciplinary research field covering:**
 - Image processing
 - Computer vision
 - PUFs
 - Crypto
 - Big Data
- **Physical object security is of:**
 - great interest for industry and especially for the Swiss industry (protection of Swiss brands)
 - great significance for end users
- **Demos after presentation slot**